

FPJB & Jabatan	Pusat Keselamatan Siber dan Revolusi Industri Digital				
Nama Program	ROS (Robot Op	peration Syste	m) Technolog	gy Development	
Sinopsis	The course is designed to provide the participants with an extensive hands-on exercise to experience the concepts and tools to practice the artificial intelligent of robot. The course will exposure the participants with the ROS technology to stimulate the development of Artificial intelligent in robotic industry. At the end of the course, the participants will have proficient knowledge on ROS technology programming and AI robot creation.				
Hasil Pembelajaran (Learning Outcomes)	 Student be able to: Explore various applications and advantages of ROS, especially for robotics applications in the industrial, construction, security and other large- scale industries. Understand the theory and experience the ROS development. Design and demonstrate AI robot in development. 				
Kaedah Pelaksanaan (Mode of Delivery)	Dalam Talian Fizikal Catatan:				
Tempoh Pengajian (Duration of Study)	Part Time	Minggu / Semester	Semester	Tempoh Pengajian	Hari Bekerja / Hujung Minggu
	Panjang Pendek Latihan Industri			3 hari	Hari Bekerja/Hujung Minggu
Kumpulan Sasaran (Target Participant)	Students, resear acquire knowled	chers, Industry ge in Robot Oj	y 4.0 related perating System	engineer, and pe m (ROS) Technol	eople who want to logy
Syarat Permohonan/ Syarat Kemasukan (Admission Requirement)	Basic Electronic	s and C progra	mming knowl	edge is required f	or this course.



MAKLUMAT PROGRAM

Struktur Kursus	Day 1			
(Course Outline) /	Chapter 1:			
Struktur Kurikulum	Session 1: Introduction to Electronics			
(Topics Covered)	Session 2: Introduction to Microcontroller			
(100100 0010100)	Session 3: C Programming			
	Chapter 2.			
	Sassion 1: Introduction to Embadded Computer			
	Session 2: Duthen Programming			
	Session 2. Fython Frogramming			
	Session 5: Introduction to OpenC v			
	Day 2			
	Chapter 3:			
	Session 1: Introduction to ROS			
	Session 2: ROS Gazebo			
	Simulation			
	Session 3: Programming Virtual ROS Robot			
	Chapter 4:			
	Session 1: Mobile Robot Development			
	Session 2: ROS Robot Programming			
	Session 2: Tele Operation of Robot			
	Session 5. Tele Operation of Robot			
	Day 3			
	Chapter 5:			
	Session 1: SLAM			
	RobotSession 2:			
	Mapping			
	Session 3: Autonomous Navigation			
	Chapter 6:			
	Session 1: Introduction to TurtleBot			
	Session 2: Teleon Turtlebot			
	Session 3: SLAM using Turtlebot			
	Chapter 7:			
	Sassion 1: Multi Pobote System using POS			
	Session 2: Virtual Multi Debote Simulation			
	Session 2. Wilti Dobot System Implementation			
	Session 5: Multi Kobol System implementation			
Yuran Kursus	RM4,000 per person			
(Course Fee)				